

## CLAIM AMENDMENTS

1           1. (currently amended) An apparatus for shaping and/or  
2 folding can bodies (11) having at least two oppositely rotating  
3 shaping tools (12 and 13) of which one is mounted on an arm (14)  
4 for radial movement, ~~characterized in that~~ wherein the arm (14) is  
5 provided with a controllable drive (15, 16, 17) comprised of a  
6 motor (15) with or without a step-down drive (16) and an increment  
7 or angle sensor (17).

1           2. (currently amended) The apparatus according to claim  
2 ~~1, characterized in that~~ wherein the arm (14) is pivotal.

1           3. (currently amended) The apparatus according to claim  
2 ~~2, characterized in that~~ wherein each pivot arm (14) is provided  
3 with two tools (13a and 13b) that are used alternately for shaping.

1           4. (currently amended) The apparatus according to ~~one~~  
2 ~~of claims claim 1 to 3, characterized in that~~ wherein by a cali-  
3 brating body (10), in particular a calibrating ring, that serves  
4 after changing of the shaping tool as a reference point for setting  
5 at a null point the increment or angle sensor (17).

1           5. (currently amended) The apparatus according to one  
2 ~~of claims claim 1 to 4, characterized in that wherein in a~~  
3 multiple-spindle carousel-type machine each arm (14) is connected  
4 with a respective externally controllable drive (15, 16, 17).

1           6. (currently amended) The apparatus according to one  
2 ~~of claims claim 1 to 5, characterized in that wherein change in the~~  
3 actual-value current output of the electrical drive relative to the  
4 angular position and the force curve derived from it is compared  
5 with a stored force curve and when a predetermined deviation is  
6 detected the respective can body is culled out.

1           7. (currently amended) The apparatus according to one  
2 ~~of claims claim 1 to 6, characterized by , further comprising a~~  
3 memory for the force curves of typical error situations.